



Efficient Simulation for Strongly Coupled Noise- Vibration-Harshness (NVH)

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E. B. Rudnyi, CADFEM



CADFEM

Background

- Joint work 2004-
- Over email
- Available online
 - ModelReduction.com/contrib/Srinivasan.Puri/

Krylov Subspace Based Direct Projection Techniques for Low Frequency, Fully Coupled, Structural Acoustic Analysis and Optimization.

R. Srinivasan Puri

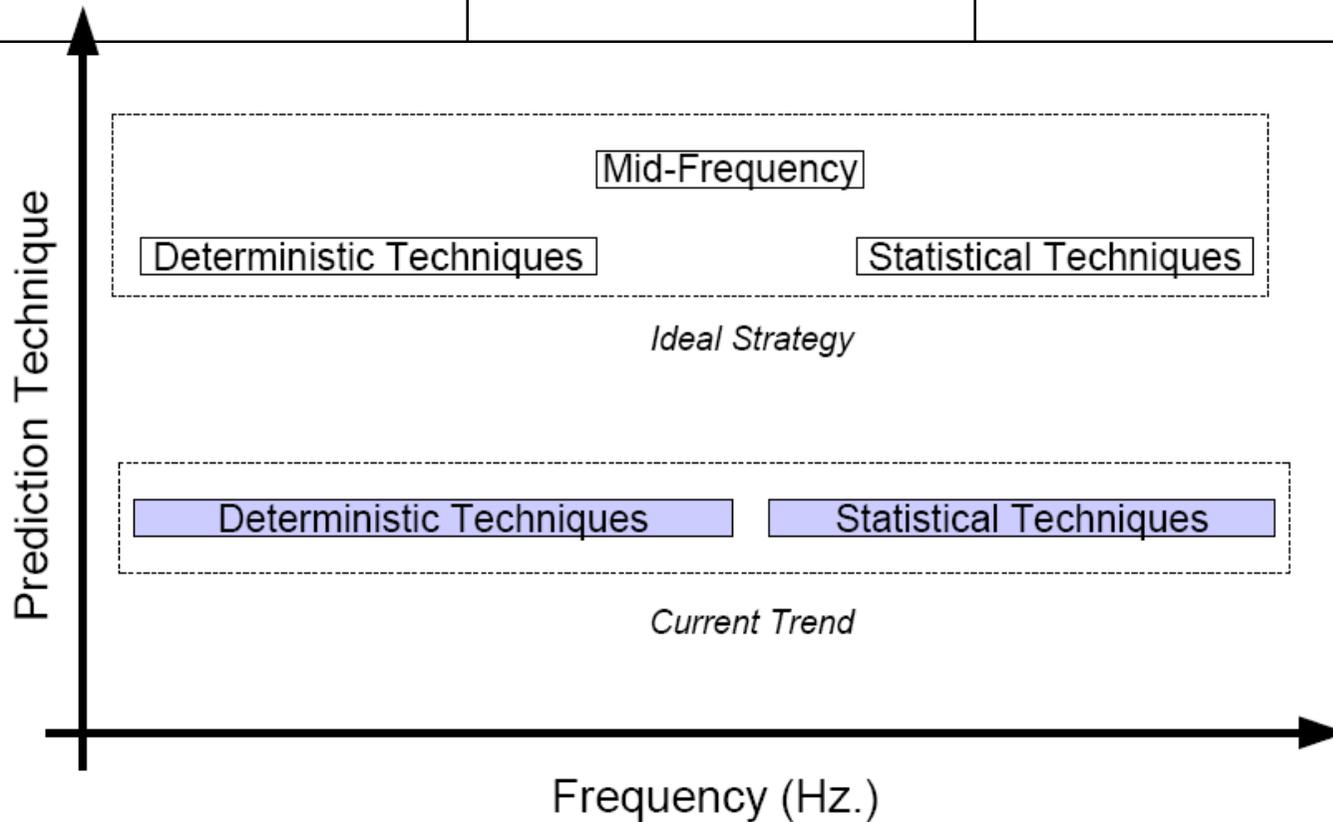
A thesis submitted in partial fulfillment of the
requirements of Oxford Brookes University
for the degree of Doctor of Philosophy.

13th March 2008



NVH Simulation

Low Frequency	Structure borne	0 – 100 Hz
Mid Frequency	Structure and air borne	100 – 250 Hz
High Frequency	Air born	> 250 Hz



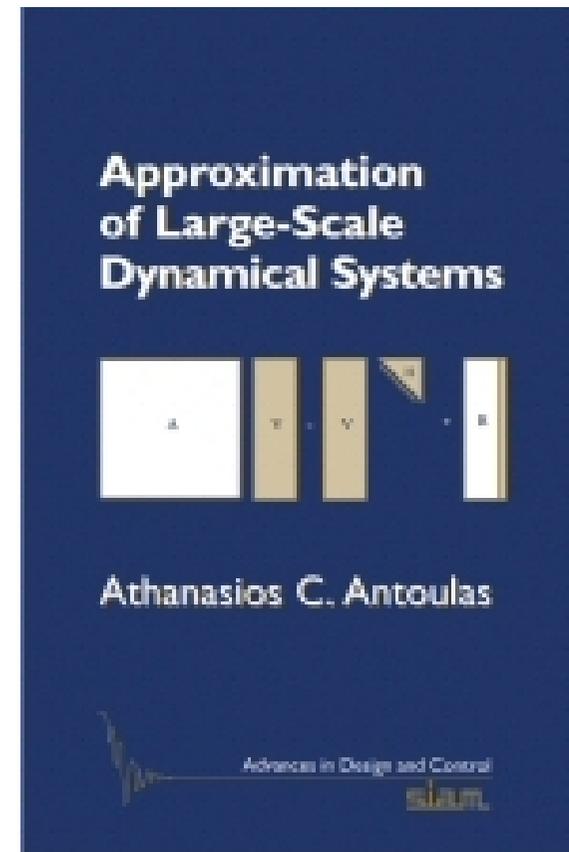
Fully Coupled Finite Element Discretization

$$\left(-\omega^2 \begin{bmatrix} M_s & 0 \\ M_{fs} & M_a \end{bmatrix} + j\omega \begin{bmatrix} C_s & 0 \\ 0 & C_a \end{bmatrix} + \begin{bmatrix} K_s & K_{fs} \\ 0 & K_a \end{bmatrix} \right) \begin{Bmatrix} u \\ p \end{Bmatrix} = \begin{Bmatrix} F_s \\ F_a \end{Bmatrix}$$

- FLUID29/FLUID30 in ANSYS
- The element size should be smaller than wavelength
 - High dimensional models
- Unsymmetric matrices

Model Order Reduction

- Relatively new technology
- Solid mathematical background:
 - Approximation of large scale dynamic systems
- Dynamic simulation:
 - Harmonic or transient simulation
- Industry application level:
 - Linear dynamic systems only



From Finite Elements to System Simulation

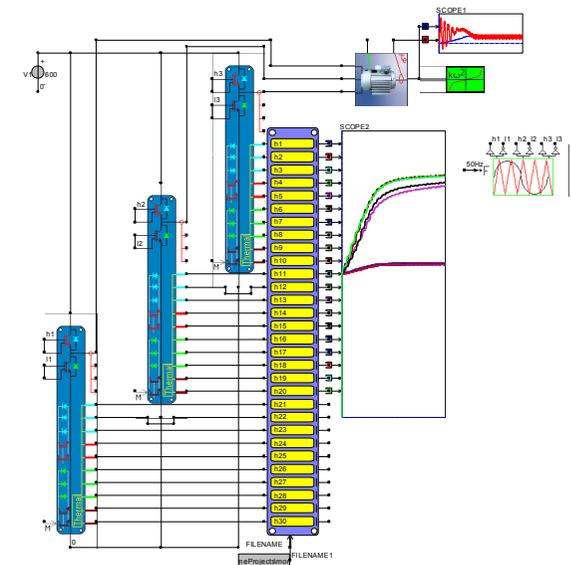
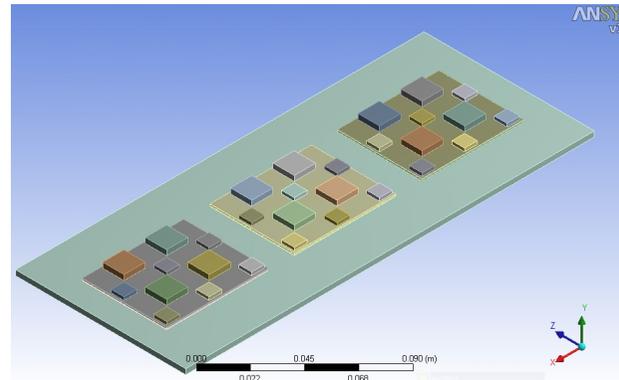
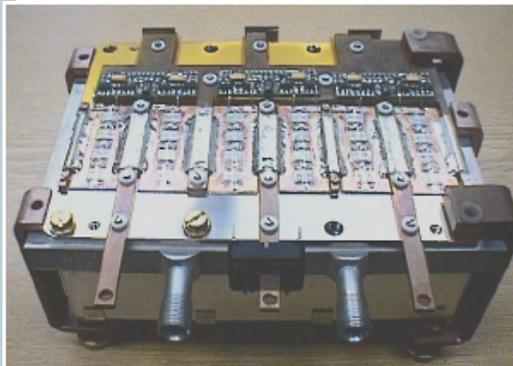
Physics &
Geometry

FEM

System of
 n ODEs

MOR

Reduced
System of
 $r \ll n$ ODEs



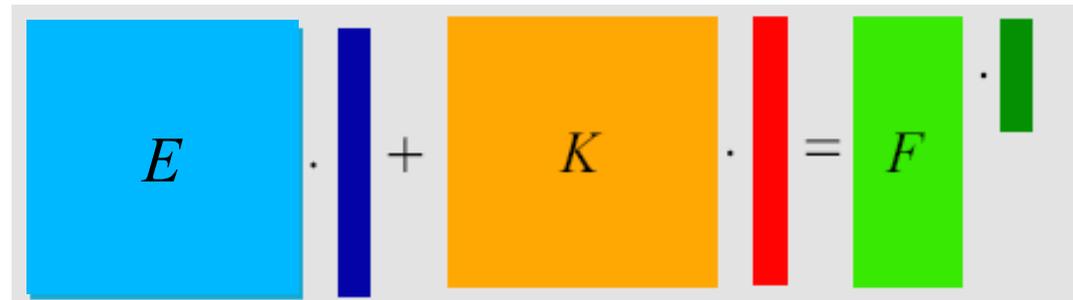
- Electrothermal Simulation with IGBTs:
 - From ANSYS Workbench to Caspoc (Eurosime 2008)

Model Reduction as Projection

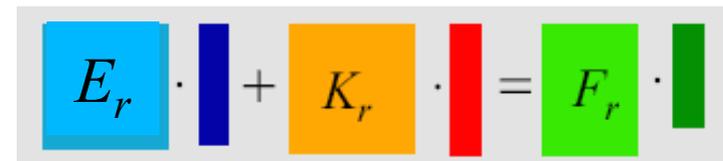
- Projection onto low-dimensional subspace

$$\mathbf{x} = V\mathbf{z} + \varepsilon$$

$$E\dot{\mathbf{x}} + K\mathbf{x} = B\mathbf{u}$$



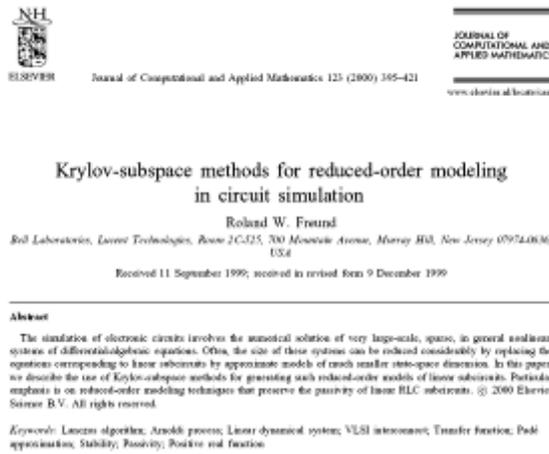
$$V^T E V \dot{\mathbf{z}} + V^T K V \mathbf{z} = V^T B \mathbf{u}$$



- How to find subspace?
- Mode superposition is not the best way to do it.

Implicit Moment Matching

- Padé approximation
- Matching first moments for the transfer function



- Implicit Moment Matching:
 - via Krylov Subspace

$$E\dot{\mathbf{x}} + K\mathbf{x} = B\mathbf{u}$$

$$H(s) = (sE + K)^{-1} B$$

$$H = \sum_{i=0}^{\infty} m_i (s - s_0)^i$$

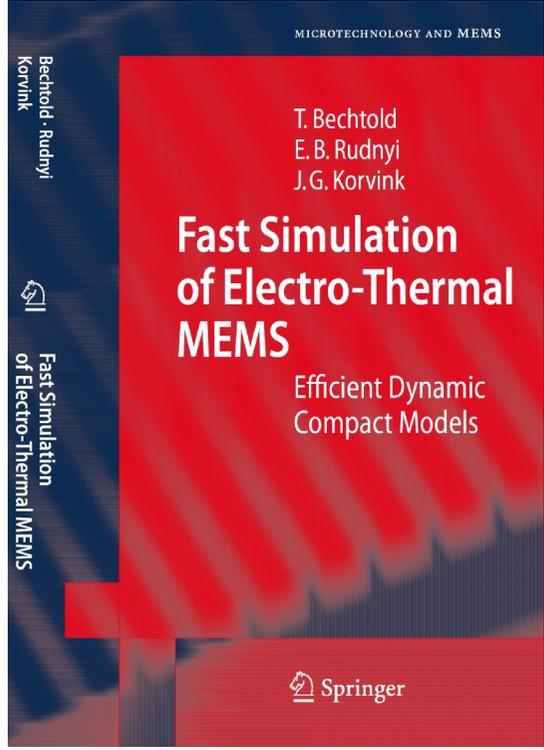
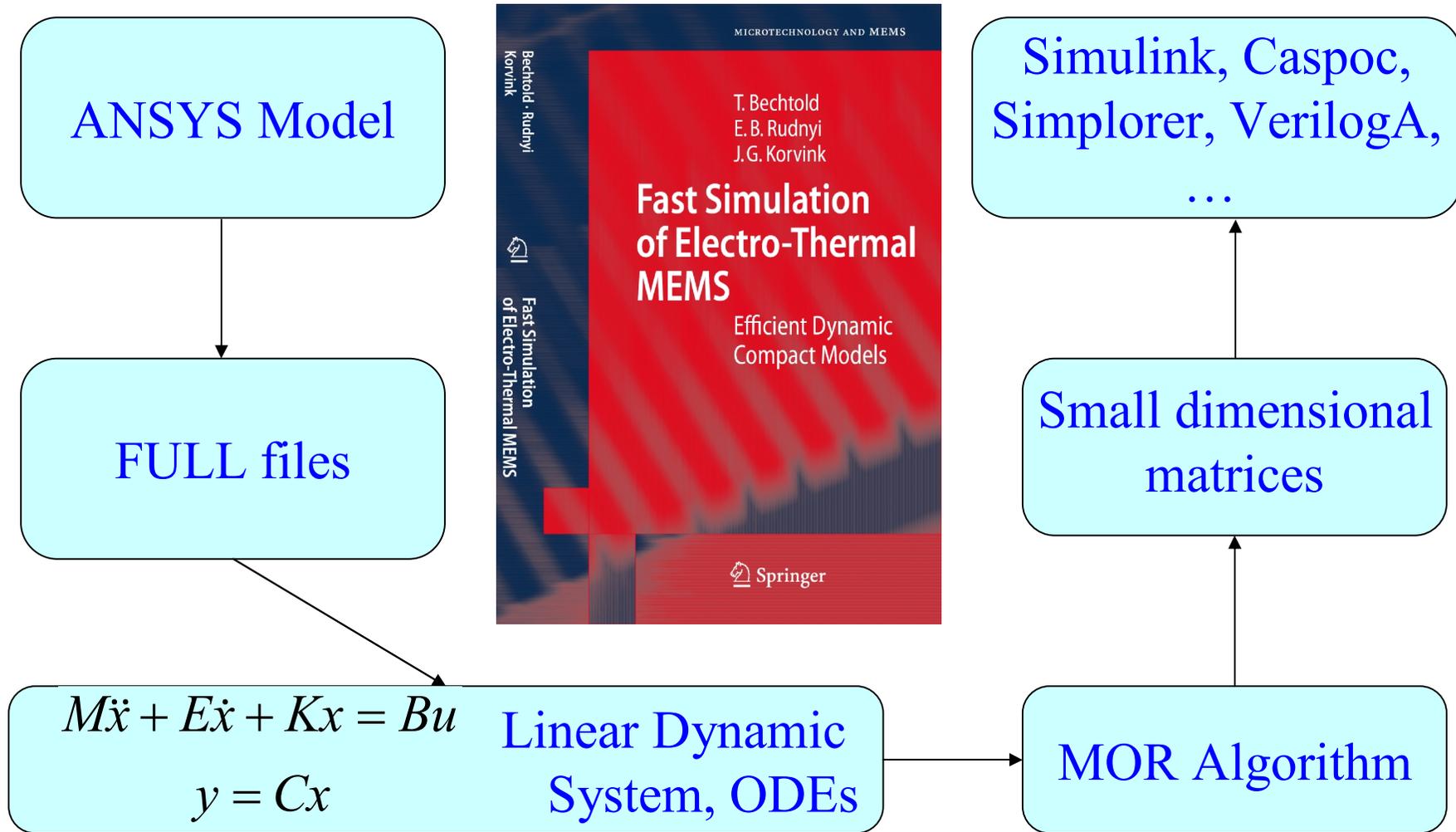
$$H_{red} = \sum_{i=0}^{\infty} m_{i,red} (s - s_0)^i$$

$$m_i = m_{i,red}, \quad i = 0, \dots, r$$

$$s_0 = 0$$

$$V = \text{span}\{\mathfrak{I}(K^{-1}E, K^{-1}b)\}$$

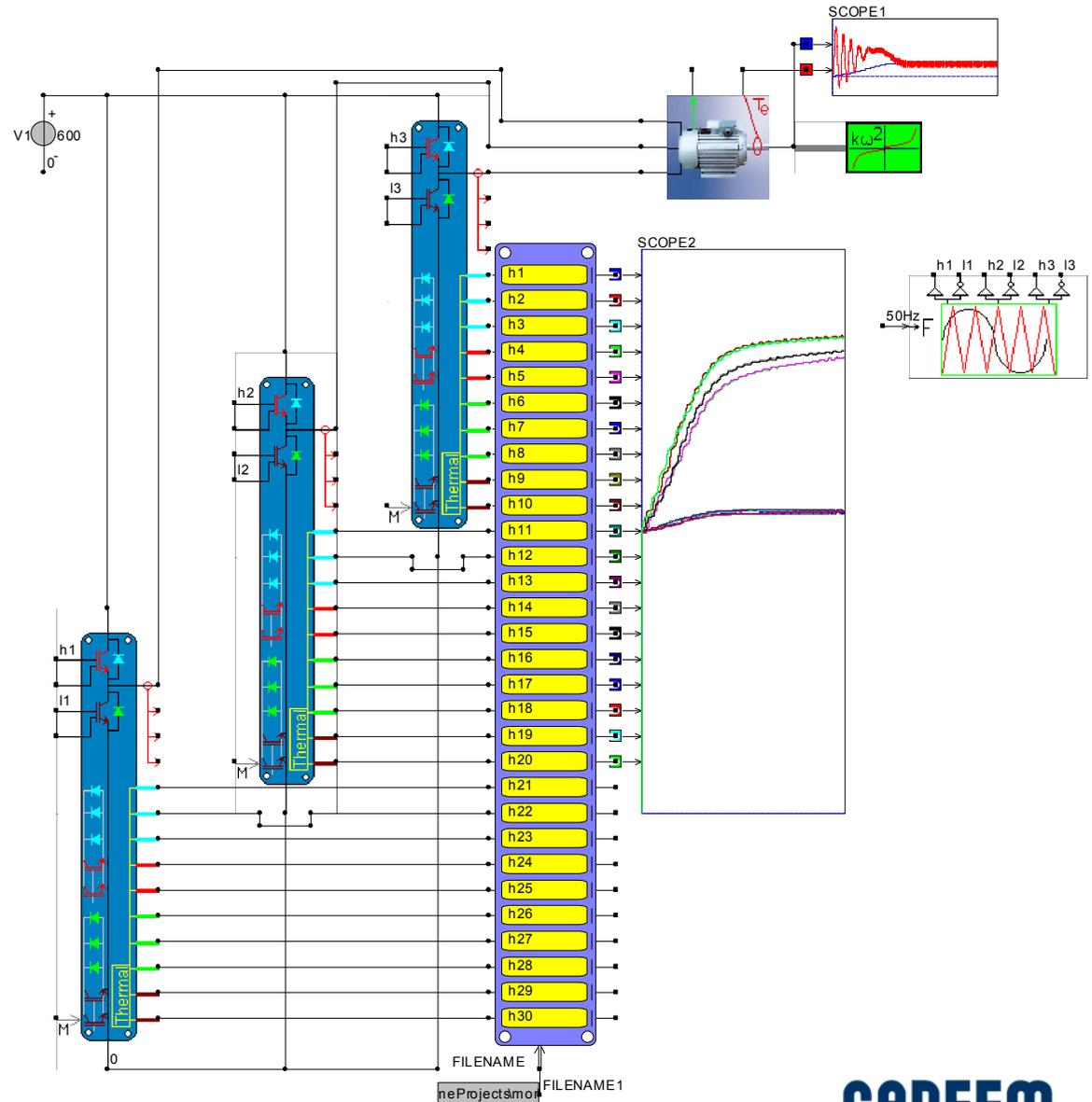
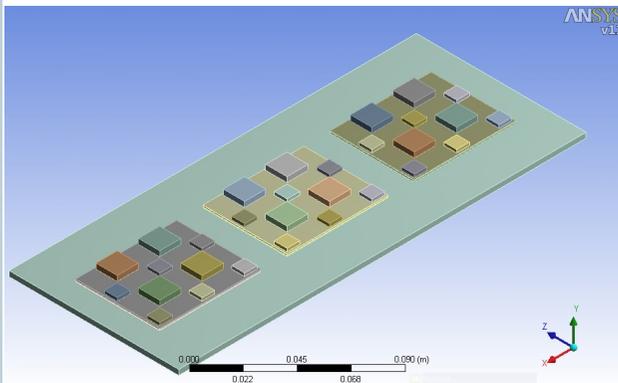
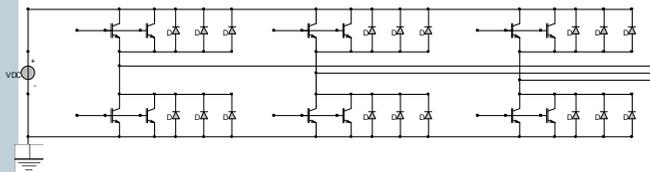
MOR for ANSYS: <http://ModelReduction.com>



Current version 2.5

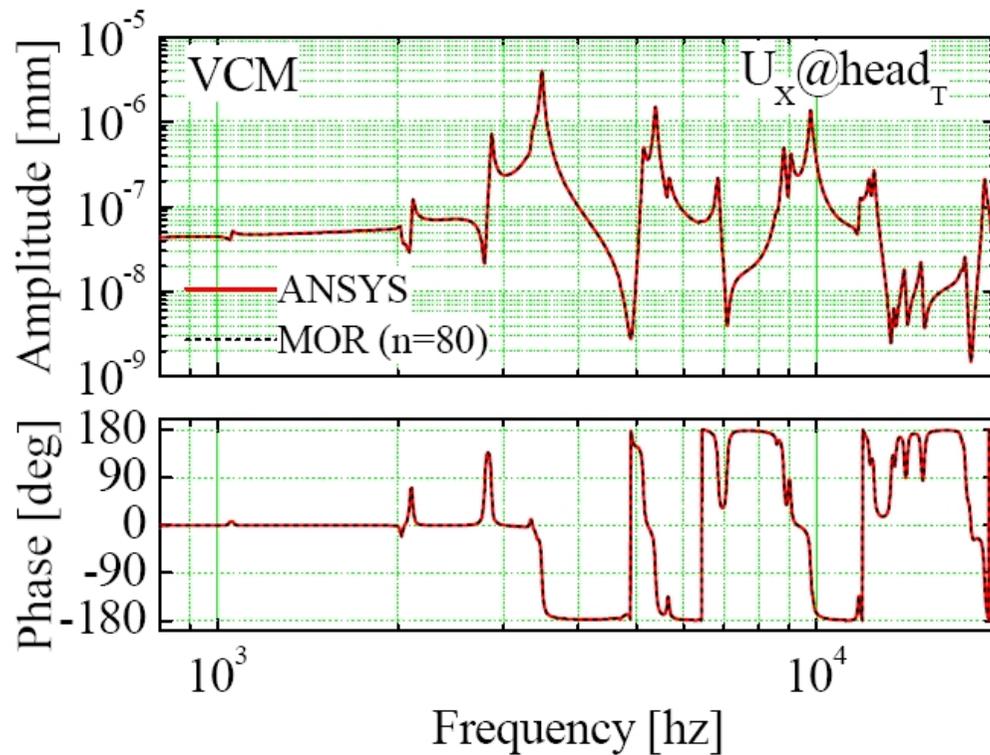
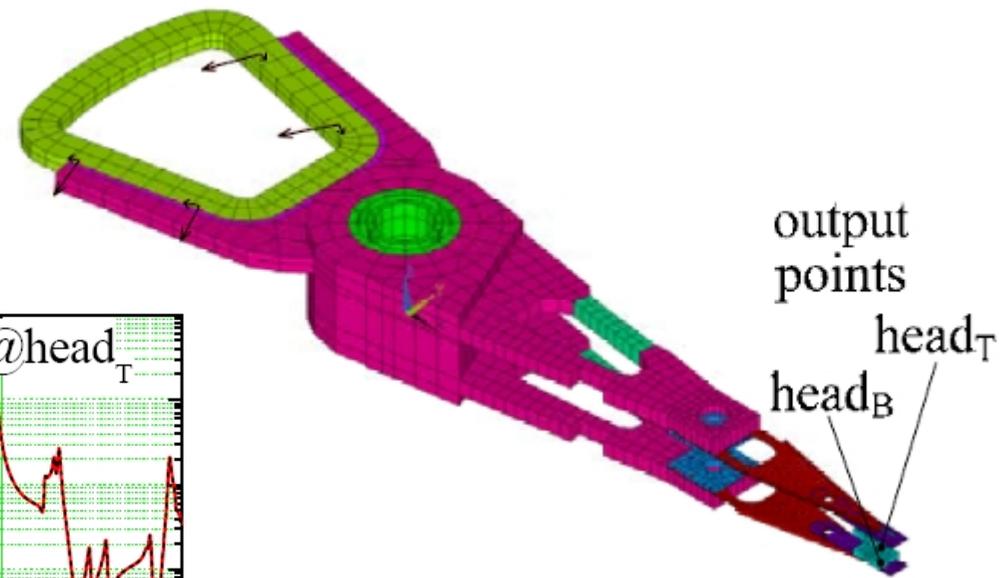
Electrothermal Simulation of IGBTs

- Eurosim 2008, Daimler, simulation with CASPOC



HDD actuator and suspension system

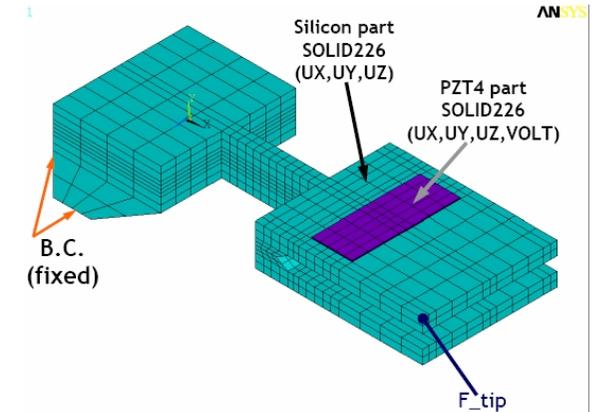
- Prof J. S. Han.
Transactions of the
KSME, A, Vol. 31,
No. 5, pp. 541-549,
2007.



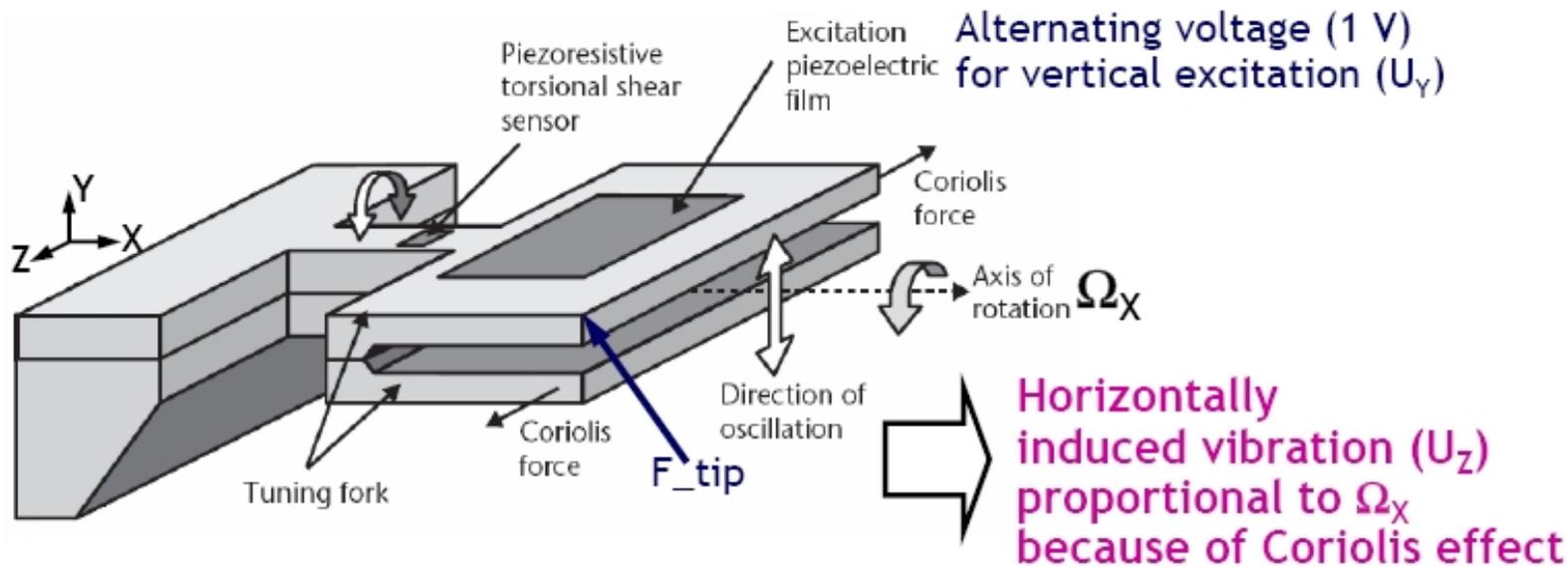
Piezoelectric Angular Rate Sensor with Coriolis Effect

- Prof J. S. Han, KSME 2008.

$$\begin{bmatrix} M & 0 \\ 0 & 0 \end{bmatrix} \begin{Bmatrix} \ddot{u} \\ \dot{V} \end{Bmatrix} + \begin{bmatrix} E & 0 \\ 0 & 0 \end{bmatrix} \begin{Bmatrix} \dot{u} \\ \dot{V} \end{Bmatrix} + \begin{bmatrix} K & K^z \\ K^{zT} & K^d \end{bmatrix} \begin{Bmatrix} u \\ V \end{Bmatrix} = \begin{Bmatrix} f \\ l \end{Bmatrix}$$



- μ-Gyroscope**
: angular velocity μ-sensor using Coriolis effect

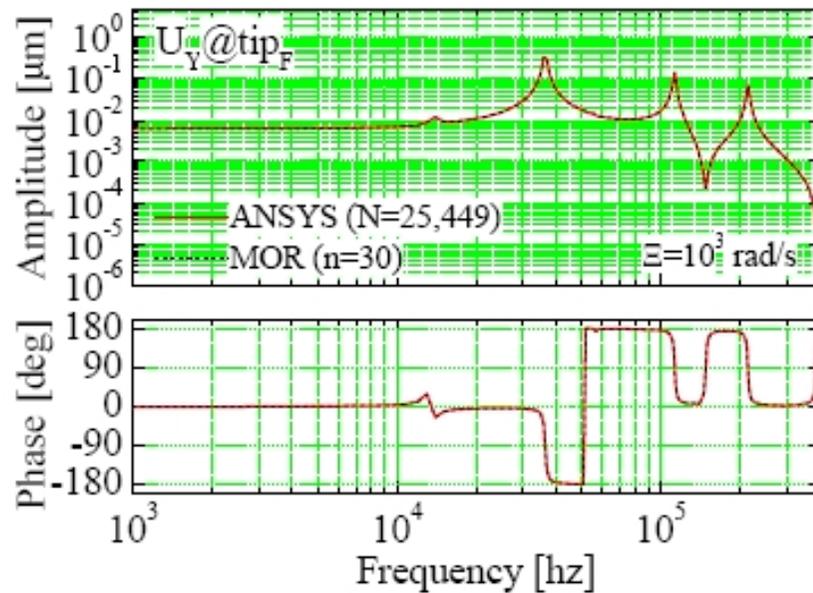


Piezoelectric Angular Rate Sensor with Coriolis Effect

- Frequency responses ($\Omega_x = 1,000$ rad/s)

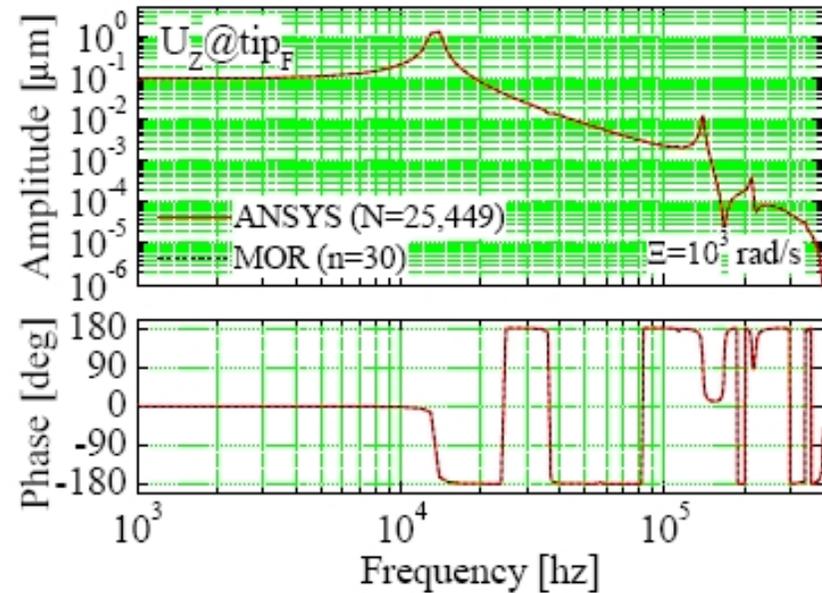
• $U_Y@tip_F$

vertical excitation



• $U_Z@tip_F$

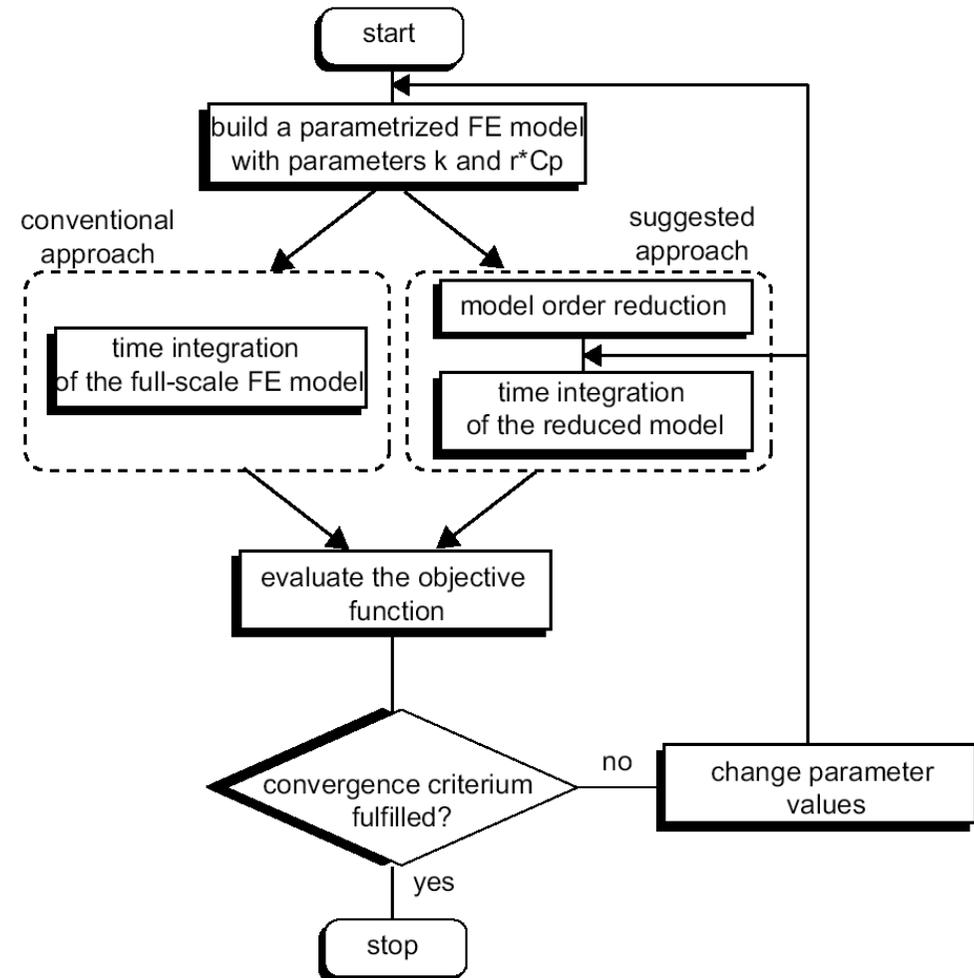
Horizontally induced vibration



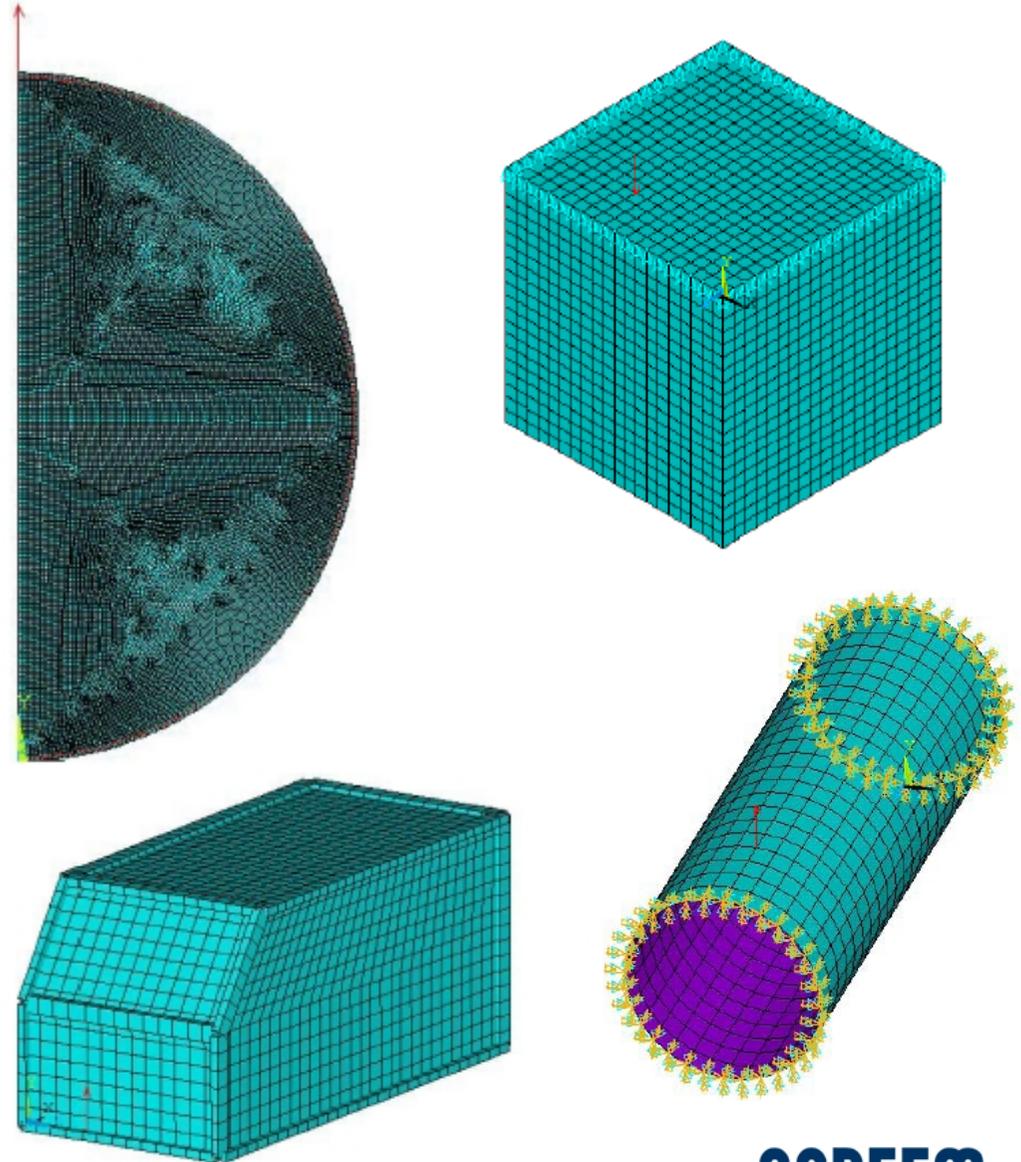
- No. of DOFs: 25,449

Model Reduction as Fast Solver

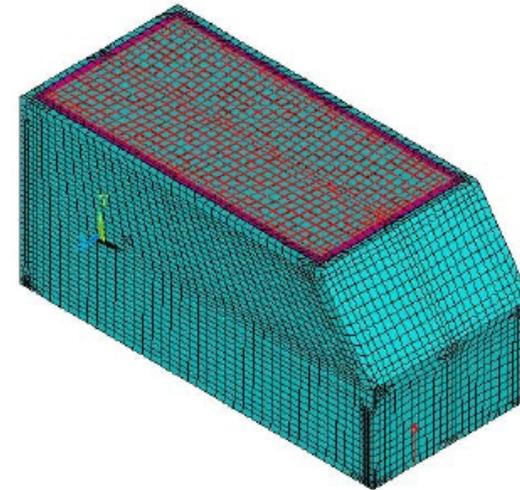
- Simulation of the reduced model is a few seconds.
- Arnoldi Process is fast:
 - Transient and harmonic response analysis for the cost comparable with that of a static solution.
- It is advantageous to use MOR even the reduced model is used only once:
 - Design,
 - Geometry optimization.



- The 2D “Acid-Test”
- 3D Plate backed air filled cavity
- 3D Plate backed Rectangular Water Filled Cavity
- Cylinder enclosing an air-filled cavity
- Demonstrator Structure: Adhesive Bonded Joint

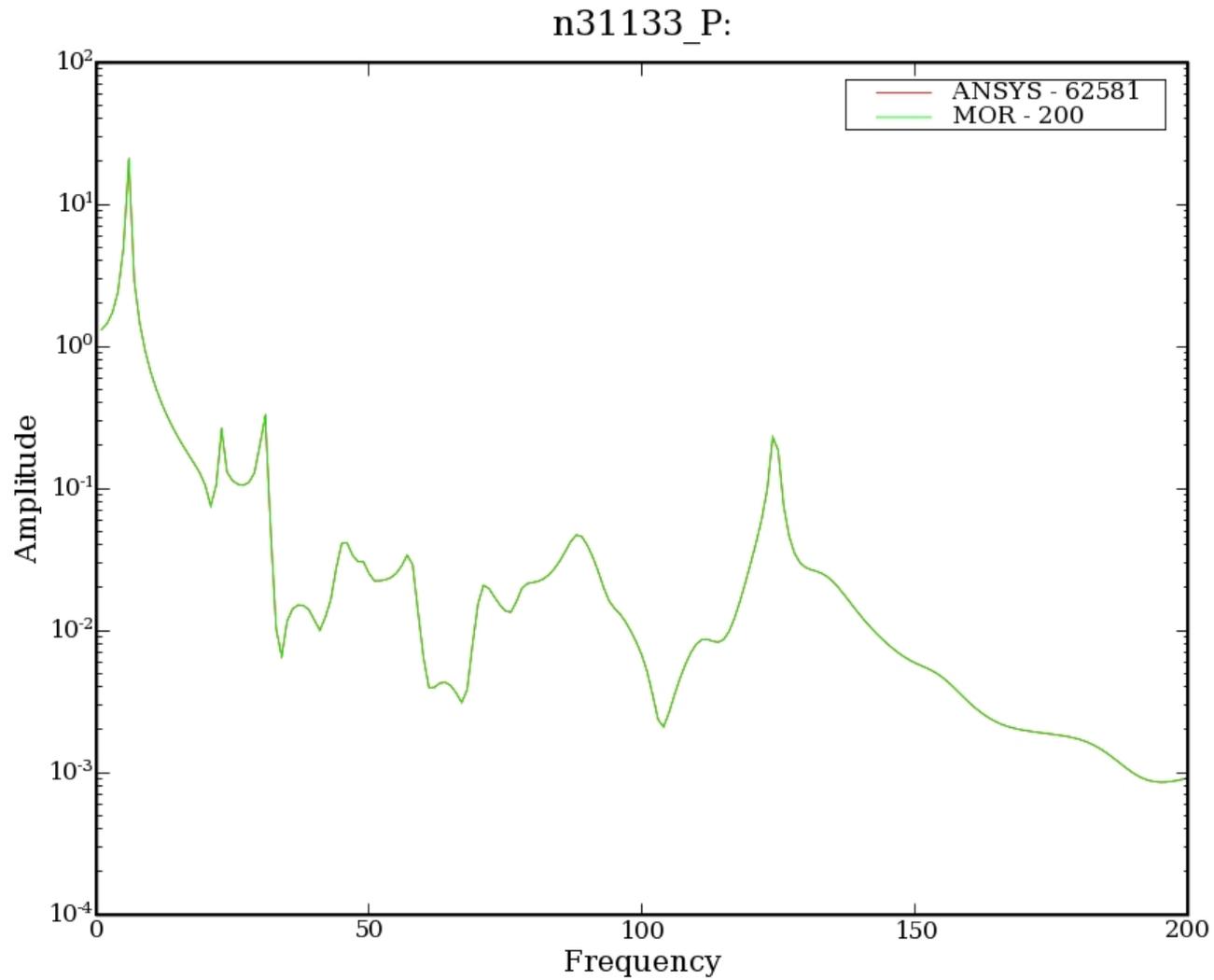


Adhesive Bonded Joint Benchmark

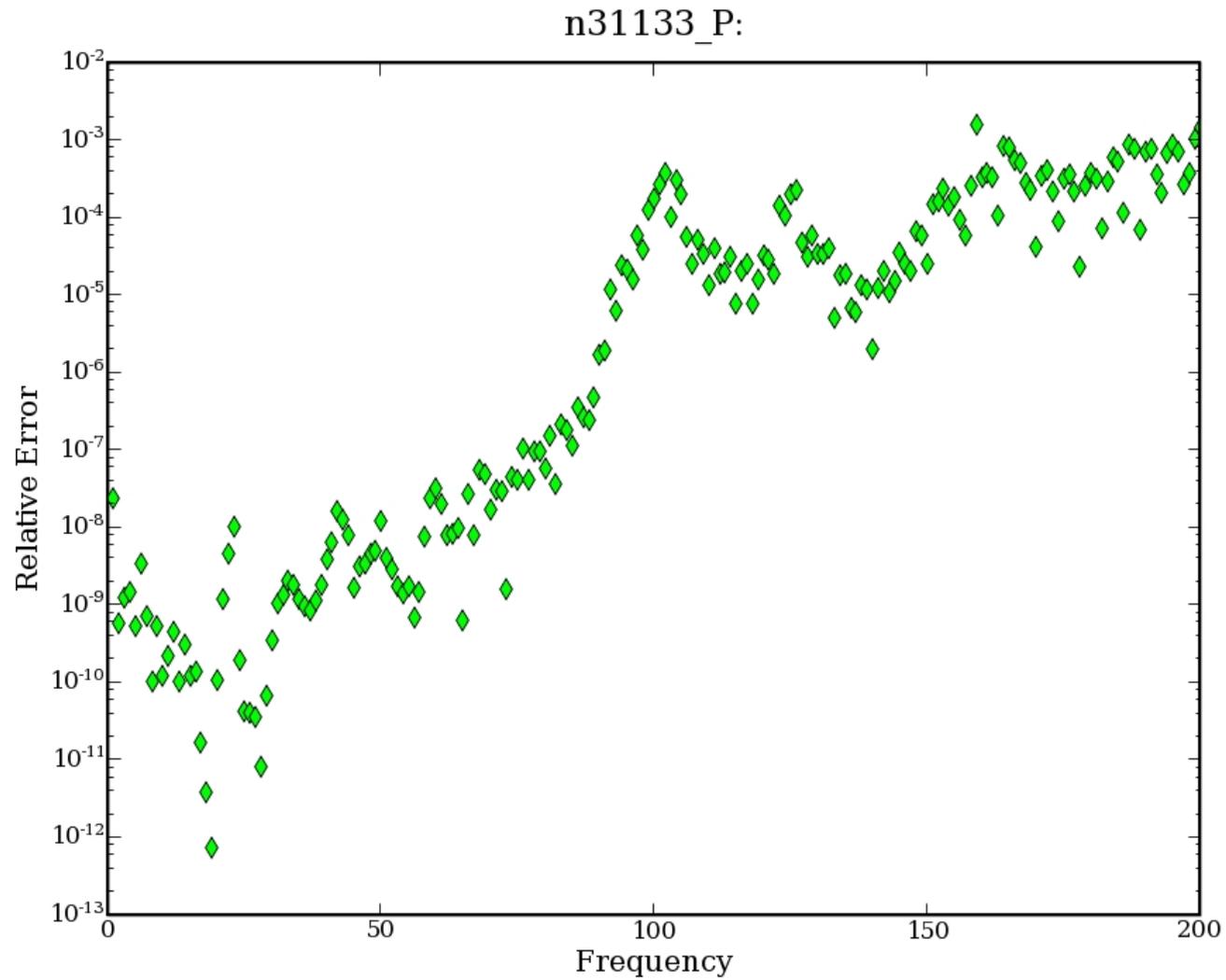


- Mechanical Structure - SHELL181
- Adhesive – SOLID45
- Fluid – FLUID30
- Single excitation point
- Global and local damping

Comparison

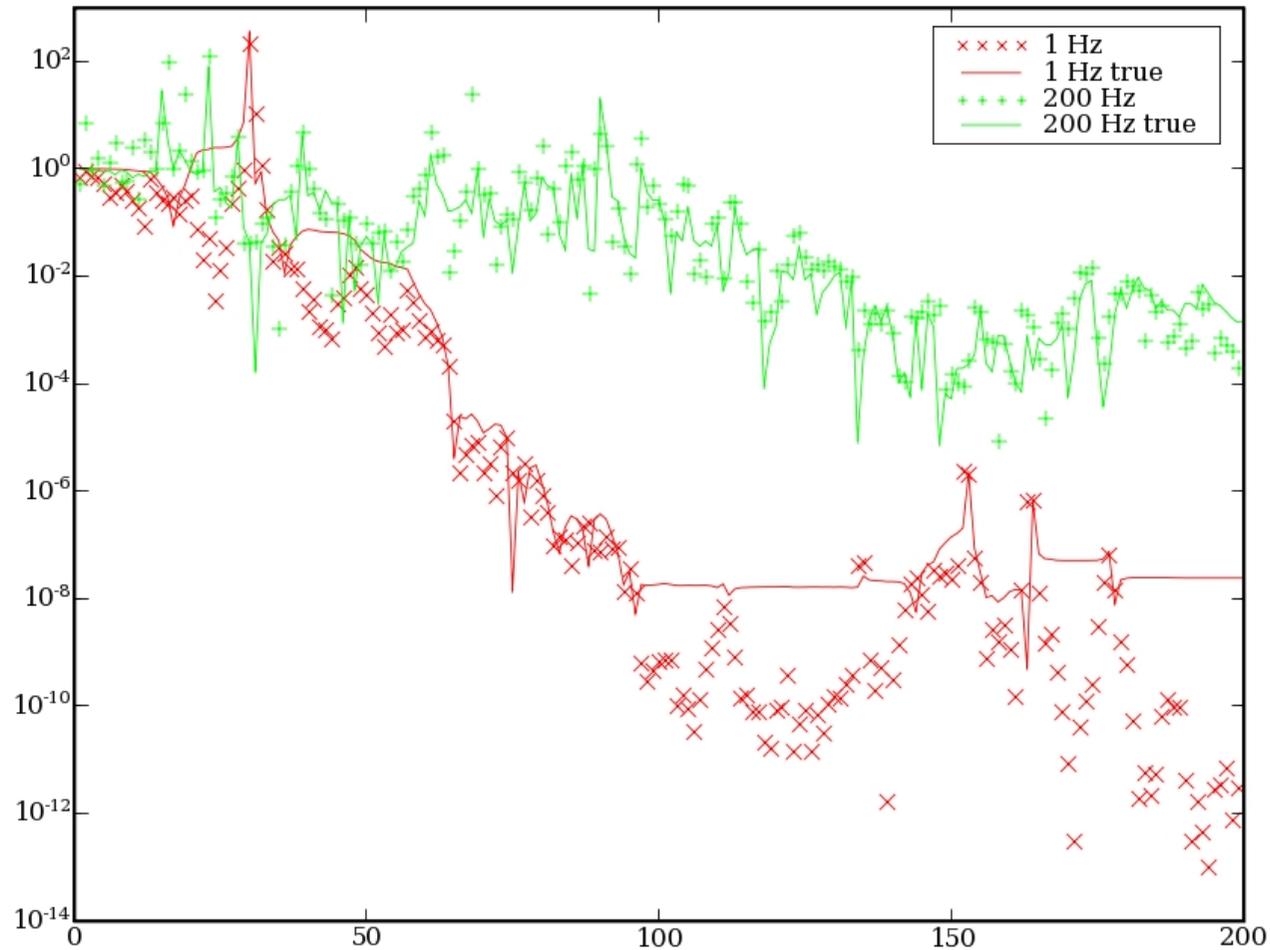


Comparison – Relative Error



Error Indicator

Relative Error vs. Dimension



- True Error

$$E_r(s) = \frac{|H(s) - H_r(s)|}{|H(s)|}$$

- Error Indicator

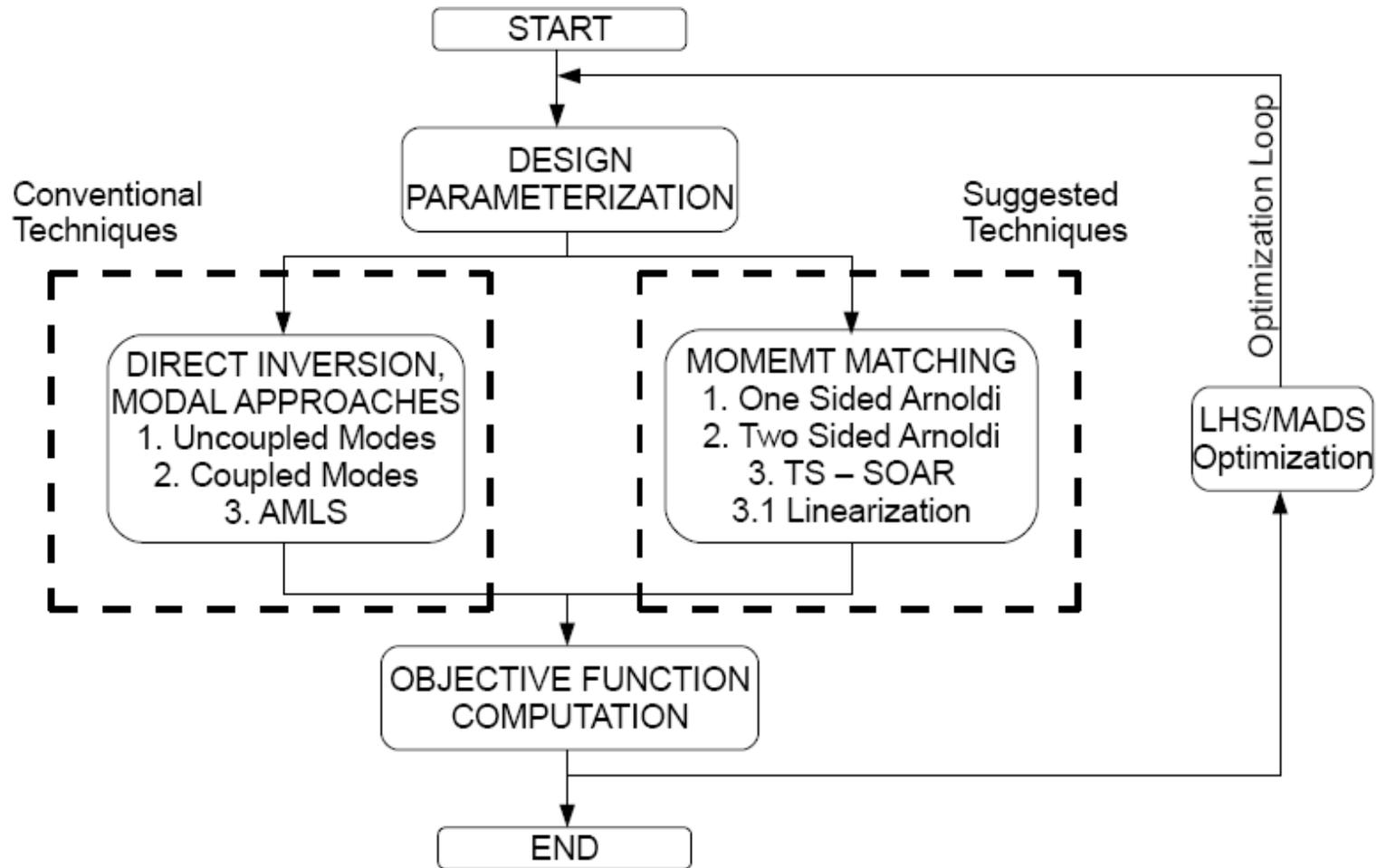
$$\hat{E}_r(s) = \frac{|H_r(s) - H_{r+1}(s)|}{|H_r(s)|}$$

$$E_r(s) \approx \hat{E}_r(s)$$

Timing

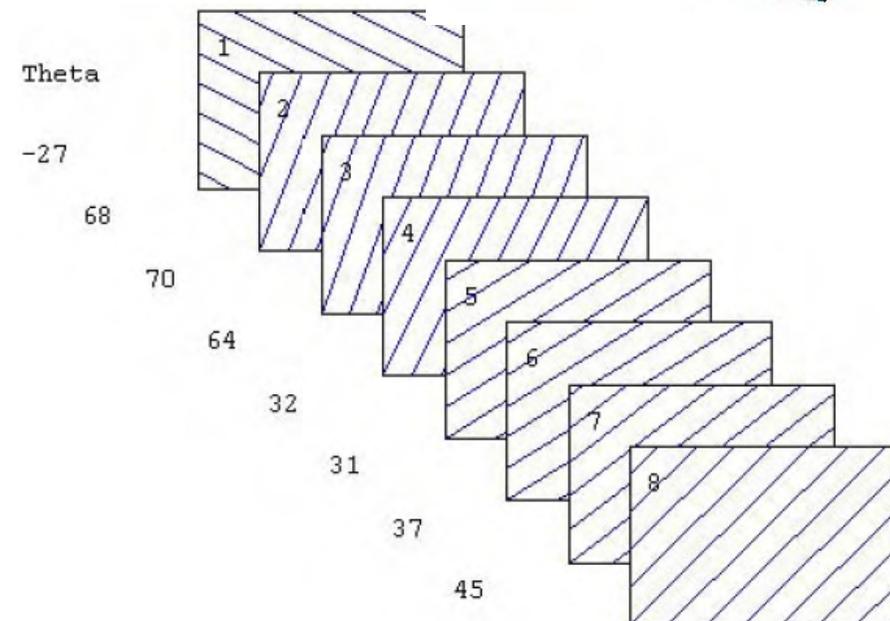
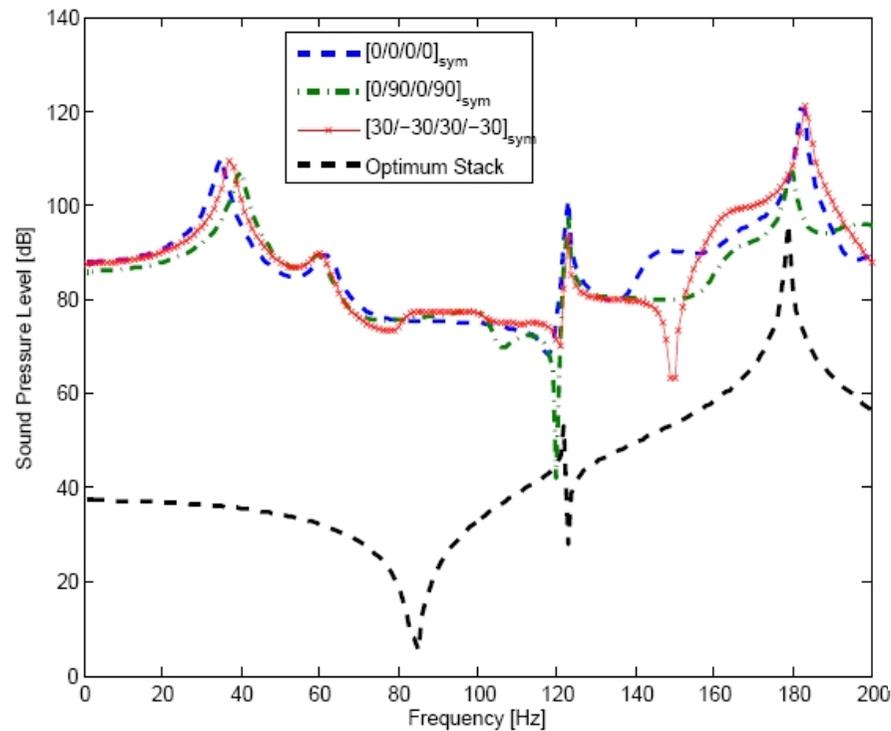
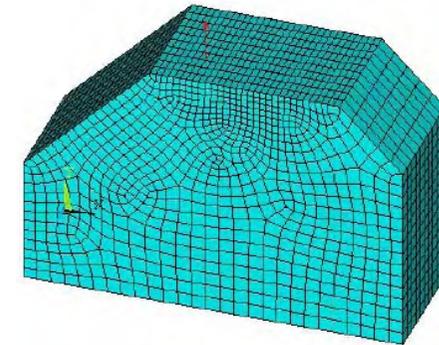
- Problem in ANSYS
 - 37988 elements, 38712 nodes, 62581 free DoFs
- Full solution in ANSYS for 200 frequencies
 - 16695 s – 4.6 hours – 83 s per frequency
 - Proportional to the number of frequencies
- MOR for ANSYS
 - Reading ANSYS files – 3 s
 - Model reduction – 170 s
 - Proportional to the number of vectors
- Simulation of the reduced model
 - 4 s

NVH Optimization

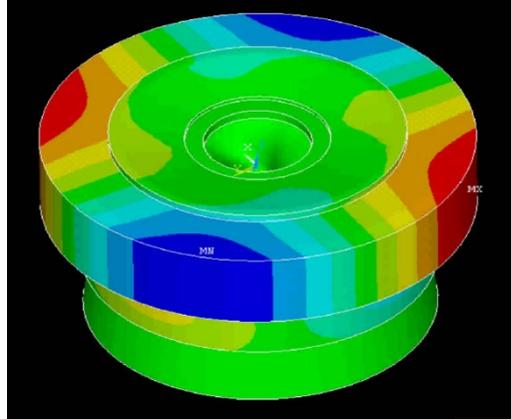
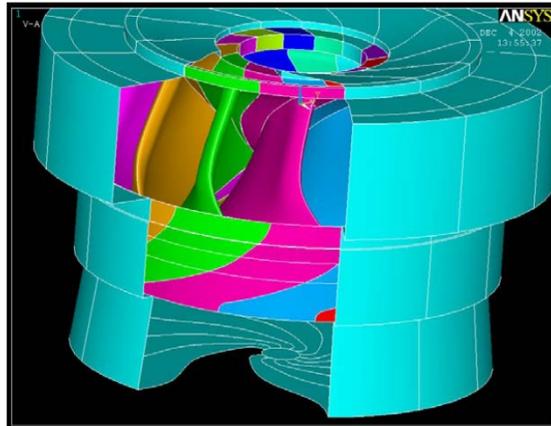


NVH Vibro-Acoustic Optimization

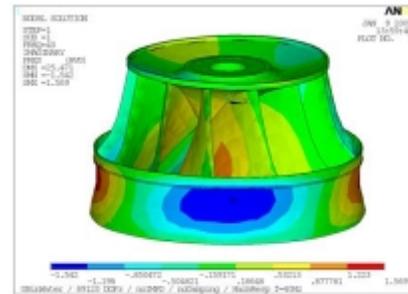
- SHELL181 to model the layered composite
- Stack of eight layers
- To find optimal lamination



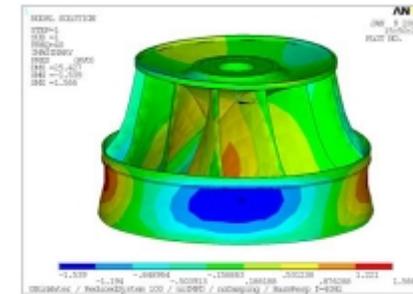
Fluid Structure Interaction at Acoustic Level



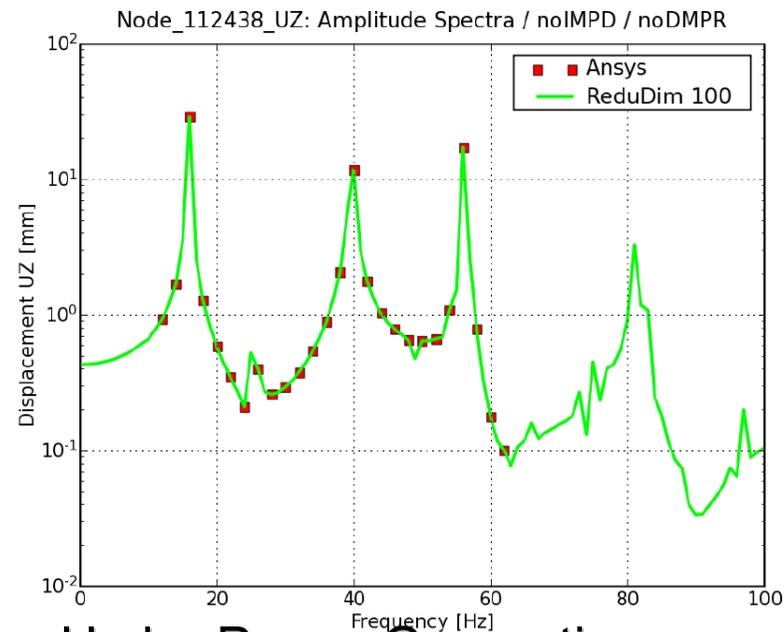
VOITH SIEMENS
HYDRO POWER GENERATION



ANSYS 90.000 DOFs



MOR 100 DOFs



By courtesy of Voith Siemens Hydro Power Generation GmbH & Co. KG

Conclusion

- Model reduction is an excellent tool to speed up NVH simulation

- Software for ANSYS is available:
 - MOR for ANSYS

- More information:
 - <http://ModelReduction.com>